Fleet Electrification for Small Vehicle On-Demand Services

Session 2A: Electrification / EV Charging

Presenter: J. Sam Lott, P.E. Automated Mobility Services, LLC Working under Dr. Stan Young – NREL Mobility, Innovation and Equity Team Lead 

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Organization of Presentation

Synopsis of NREL Automated **Mobility District Research**

Automated Fleet Operations in On-**Demand Transit Network Service**

Fully Integrated Battery Charging Systems and Infrastructure



ITS Texas Annual Meeting September 29, 2022 San Marcos, TX

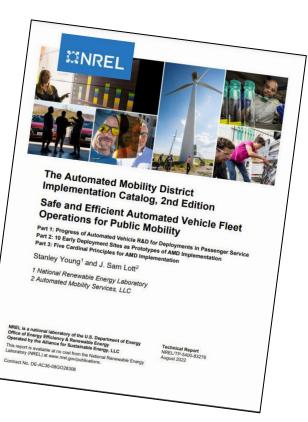
Synopsis of NREL Automated Mobility District Research

Development of Concepts for Automated/Autonomous Vehicle (AV) Fleets as Essential Building Blocks of Future Automated Mobility Districts (AMDs)





Automated Mobility District Implementation Catalog Series is Foundational



<u>The Automated Mobility District</u> <u>Implementation Catalog 2nd Edition:</u> <u>Safe and Efficient Automated Vehicle</u> <u>Fleet Operations for Public Mobility</u>

- Coauthors: Stanley Young; J. Sam Lott
- Published July 2022: Golden, CO: National Renewable Energy Laboratory. NREL/TP-

https://www.nrel.gov/docs/fy22osti/83276.pdf



<u>The Automated Mobility District Implementation Catalog</u> <u>2nd Edition – Safe and Efficient Automated Vehicle Fleet</u> <u>Operations for Public Mobility</u>

- Part 1 Progress of Automated Vehicle R&D for Deployments in Passenger Service
- Part 2 10 Early Deployment Sites as Prototypes of AMD Implementation
- **Part 3** Five Cardinal Principles for AMD Implementation



10 Early Deployment Sites Tracked Through Phase 1 and Phase 2 Research

<u>Site #1</u>: Columbus, OH <u>Site #2</u>: Arlington, TX <u>Site #3</u>: Las Vegas, NV <u>Site #4</u>: Jacksonville, FL <u>Site #5</u>: Houston, TX

<u>Site #6</u>: M-City, Univ. of Michigan, Ann Arbor, MI <u>Site #7</u>: Rivium, City of Capelle aan den Ijssel, Netherlands <u>Site #8</u>: Denver, CO

Site #9: Gainesville, FL

Site #10: Babcock Ranch, FL



Progress of AV R&D for Deployments in Passenger Service

- Challenge of preparing for mixed traffic operations.
- Improved equity of access in extended AV service within the city.



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Early Deployment Sites as Prototypes of AMD Implementation

- Multimodal environment brings added complexity of operations.
- Large scale deployments will require Intelligent Roadway Infrastructure.



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Early Deployment Sites as Prototypes of AMD Implementation

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Industry Trends Show AV Technology Will Occur Primarily with Battery-Electric Vehicle Drive Trains



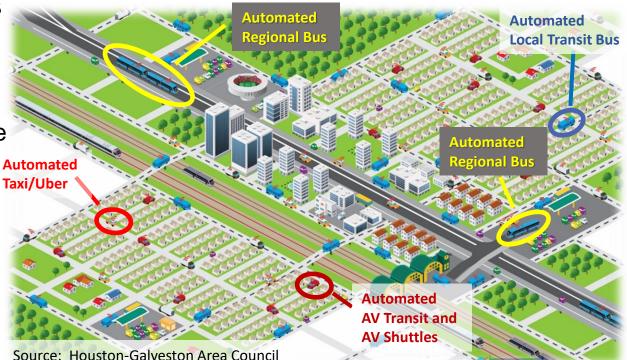
AMD Concept Has Multiple AV Fleets Operating Within the District

AMDs in Urban Districts and Major Activity Centers with AV Circulation and FM/LM Connections

to High-Capacity Transit Automated BRT and local bus lines.

- Automated AV fixed route transit & on-demand service transit modes.
- AV on-demand car services and AV taxi fleets.

 How will BEVs be charged?



<u>AV/EV Shuttle Deployment in Rivium Business Park</u> near Rotterdam in the Netherlands Will Be a Crossover Technology



Crossover APM technologies now beginning to enter the Automated/Autonomous Vehicle (AV) marketplace. The experience with systemlevel operations is an important aspect of this crossover influence in the automation of roadway transport systems.



Source: 2getthere/ZF

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Automated Fleet Operations in On-Demand Transit (ODT) Network Service

Passenger Transport along a Network of Roads or Dedicated Transitways with AV Fleet Vehicles Dispatched in Response to Passenger Demand Calls/Requests





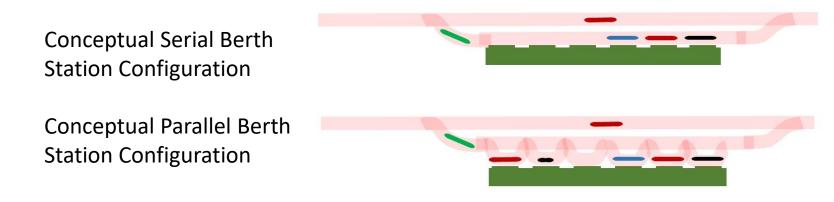
Distinctions of ODT Operations Compared to Fixed Route Transit

- On-Demand Service direct from Origin to Destination Station similar to "Ride-Hailing" service, or "Robo-Taxi" operations.
- Off-roadway boarding station/curbfront allows for a robust demandresponse dispatching of individual vehicles to carry their passengers:
 - Station/curb dwell time not fixed, with extended dwell possible to load multiple travel parties.
 Source: City of Arlington, TX
 - No other stops in-between Origin and Destination stations/curbs.
- Several prototype ODT network system concepts are now operating in early AV technology development pilot deployments.



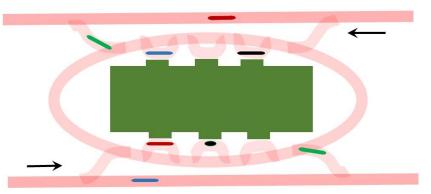
Station and Curbfront Configurations are Critically important to System Throughput Capacity

- How vehicle berthing is provided at boarding locations is fundamentally important for small-to-medium size vehicle ATN systems.
- Individual vehicle berths in parallel versus serial configuration have practical and strategic benefits to station performance and capacity.



Example of a Parallel Berth Station Configuration

Source: The Boring Company website – https://www.boringcompany.com/lvcc Accessed 23 January 2022

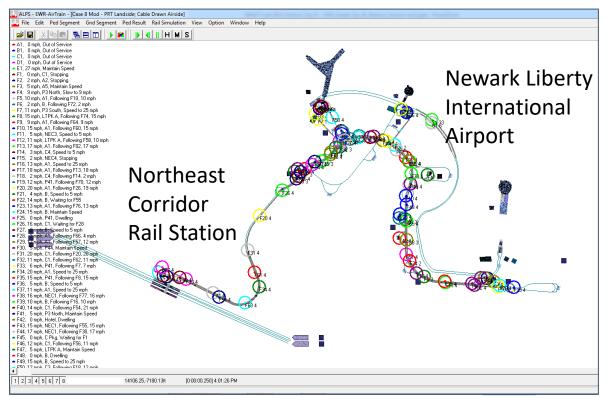






A TRB 2016 Presentation Addressed Facility Design Considerations for High Speed Rail (HSR) Intermodal Stations with ATN Feeder Service

- Small vehicle technology (4-passenger) with sharedride operations.
- System performance is impacted by remote NEC Station location.
- Initial studies showed an inability to sustain adequate vehicle supply to the NEC Rail Station during airport access peak periods, creating "empty vehicle starvation" at the remote rail station facility.





Key ODT Considerations: Empty Vehicle Supply and Station Configuration

100000

- A1, 0 mph, Out of Service
- ► B1, 0 mph, Out of Service
- C1, 9 mph, Out of Service
- D1, 10 mph; Speed to 40 mph
- E1, 0 mph, 0 pening Doors
- F1, 26 mph, Maintain Speed
- G1, 5 mph, C4, Maintain Speed
- G2, 0 mph, B Pkg, Idle
- G3, 22 mph, P42, Slow to 22 mph
- G4. 0 mph. P3 North. Stop and Waiting for G111
- G5, 25 mph, P3 South, Maintain Speed
- G6, 5 mpb, A1, Maintain Speed
- G7, 15 mph, C1, Speed to 25 mph
- G8, 5 mph, C Pkg, Maintain Speed
- G9, 17 mph, P44, Maintain Speed
- G10, 0 mph, P3 South, Stop and Waiting for G114
- G11, 25 mph, PATH Storage, Maintain Speed
- G12, 12 mph, P2, Slow to 5 mph
- G13, 0 mph, P3 South, Stop and Waiting for G10
- G14, 0 mph, A9, Idle
- G15, 0 mph, A10, Following G81, 0 mph
- G16, 5 mph, A6, Speed to 5 mph
- = G17, 0 mph, PATH Storage, Following G44, 0 mph
- G18, 0 mph, NEC1, Idle
- G19, 25 mph, LTPK A, Maintain Speed
- G20, 0 mph, NEC Storage, Idle
- G21, 0 mph, NEC Storage, Stop and Waiting for G20
- G22, 0 mph, NEC Storage, Stop and Waiting for G21
- G23, 0 mph, NEC Storage, Stop and Waiting for G22
- G24, 0 mph, NEC Storage, Stop and Waiting for G23
- G25, 0 mph, NEC Storage, Stop and Waiting for G24
- G26, 0 mph, NEC Storage, Stop and Waiting for G25
- G27, 0 mph, NEC Storage, Stop and Waiting for G26
- G28, 0 mph, NEC Storage, Stop and Waiting for G27
- = G30, 0 mph, NEC Storage, Stop and Waiting for G29
- G31, 0 mph, NEC Storage, Stop and Waiting for G30
- G32, 0 mph, NEC Storage, Stop and Waiting for G31
- G33, 0 mph, NEC Storage, Stop and Waiting for G32
- G34 0 mph NEC Storage Stop and Waiting for 6
- G35, 0 mph, C1, Following GN04, 0 mph
- G36, 5 mph, B Pkg, Maintain Spea
- G37. 5 mph. P41. Maintain Speed
- G38, 0 mph, P3 South, Idle
- G39, 5 mph, PATH Storage, Maintain Speed
- G40, 17 mph, B1, Slow to 15 mph
- G41, 5 mph, B3, Maintain Speed
- G42, 5 mph, C1, Slow to 5 mph
 G42, 0 mph, C1, Slow to 5 mph
- G43, 9 mph, PATH Storage, Speed to 9 mph
 G44, 0 mph, C Pkg, Following G90, 0 mph
- G44, 0 mpn, CPKg, Folio
 G45, 0 mph, NEC1, Idle
- G46, 5 mph, P41, Maintain Speed
- G47, 0 mph, B1, Dwelling
- G48, 5 mph, B1, Maintain Speed
 G49, 14 mph, A1, Maintain Speed
- 1 2 3 4 5 6 7 8

7511.99,-5435.08ft

[0:00:02.000] 6:12:43 AM

Empty vehicles waiting in a Storage Facility for dispatch

Time: 6:12:46 a.m.

Station Configuration Requires Parallel Berths

> Surge of passengers from departing train flow toward ATN station platform

> > 18

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Fully Integrated Battery Charging Systems and Infrastructure

Multiple AV fleets in operation within an AMD will be best served by a common automated battery charging system and infrastructure.





BEV Fleet Operations Requires Dedicated Infrastructure

| Small Vehicle Charging Levels Level 1 Charging Station | Charging Time (Hrs)* | Power Supply (Amps @Voltage) | Power (kW) |
|--|-------------------------|---------------------------------|---------------|
| 110v house circuit plug-in | 12+ | 20 A @120 VAC | 2.4 |
| • 240v house circuit plug-in | 8+ | 40 A @240 VAC | 9.6 |
| Tesla Home 100kWh Charging Unit | 6+ | 50 A @240 VAC | 11.5 |
| Level 3 DC Fast Charging Station • Commercial Grade Fast-Charge Stat | ion 2+ | 120 A @240 VAC | 36 |
| Tesla Supercharger Station | 0.75 | 250A @480 VAC | 120 |
| * Reference – Tesla Model X, 200 mile Ran | ige | | |

Full Size Bus Battery Charging Requires Special Infrastructure Bay Area EV Bus Operator

- "Deep" Charging (depot) 90kW with 2-4 Hours Charge Time
- On-Route Charging (periodic) 50 kW 10 minute Charge Times

Proterra EV Bus Data

- 50-60 Mile Range (periodic) 10 min. periodic charge time, 350 KW max charge rate
 Uses Overhead Fast-Charge Technology
- 150-200 Mile Range (depot) 3 hour charge time
- 250-350 Mile Range (depot) 4-5 hour charge time These values have been rounded-off for simplicity of presentation

In comparison to Small Vehicle ODT Transit Network Service:

Fixed Route Bus Operations allow fewer dedicated charging stations to adequately serve the operating fleet along the "line-haul" operating route.

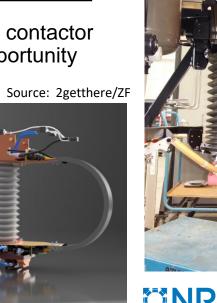


Battery Charging Aspects of the System Design Can Add to the Complexity of Automated Fleet Operations

DC Fast Charge Power Transfer can be Accomplished with High-Precision Docking of AV Fleet Vehicles at Stations

Rivium 3.0 vehicle technology applies an automated contactor deployment device in selected station berths for "opportunity charging" with DC fast charge equipment.









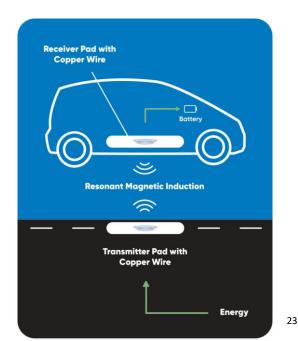
Inductive Power Transfer for Moderately High Battery Charging Rates Will be an Option with Semi-Precise Station Docking of AV Fleets

Volvo will test wireless charging with EV Taxis

Mar. 4, 2022 Autoweek Magazine

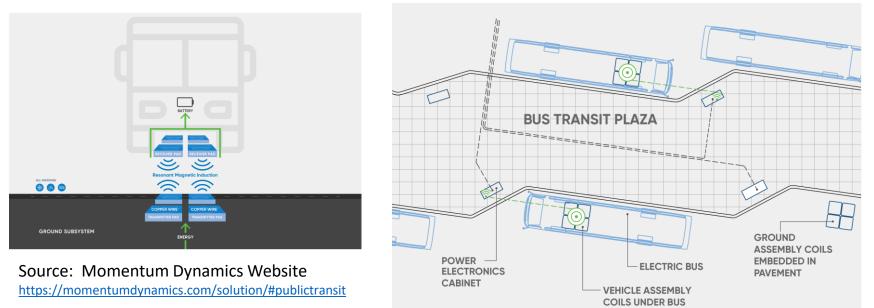


Source: Momentum Dynamics Website https://momentumdynamics.com/solution/#publictransit



Inductive Power Transfer for Contactless Battery Charging an Option for Large and Small Vehicles in an AV Fleet Operation

Inductive Power Transfer charging will require careful design of vehicle body for protection of passengers onboard from potentially harmful effects.



Battery Charging Philosophy Affects System Design and Fleet Size Depot or Storage Area Charging Takes Vehicles Out of Service

- Allows placement of charging stations where it is convenient and cost effective.
- Manual plug-in charging more manageable with Operations Staff.
- Deep Charging in Depot and a few storage locations can supplement other charging.
- Fleet size impacts can be as high as +20% to +30% extra vehicles.





Battery Charging Philosophy Affects System Design and Fleet Size

Opportunity Charging in Stations Keeps Vehicles in Service While Maintaining a Ready-Dispatch Vehicle Status

- Station berth charging system provides for fully automated charging.
- Power transfer design for vehicle/ charging station interface is a key design factor.
- Precision Docking in station berths is best for a general design requirement.
- Parallel Berth configuration allows an extended vehicle dwell time when needed for battery charging.



Battery Charging Philosophy Affects System Design and Fleet Size



A mixed design with both **Opportunity Charging in the** station berths and Deep Charging at strategically located off-line storage locations will be the best approach for Small Automated Vehicles operating in managed fleets in an On-Demand Transit Network System.

Conclusions on Fleet Electrification for Small Vehicle Fleet Operations with ATN Type of On-Demand Services

- 1. AV technology is a natural fit with battery-electric vehicle fleets.
- 2. Fully automated AV fleets will be best served by fully automated battery charging capability.
- **3.** Off-line stations with parallel berth configuration allow vehicles to dwell for an extended time until they are dispatched into service.
- 4. Battery charging in station berths is an excellent option for "opportunity charging" during off-peak periods without disrupting station capacity and performance levels.
- 5. "Deep Charging" of vehicle batteries with high-power charging stations can also be accomplished in fully automated mode in the depot or in storage areas specifically designed for this purpose.

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Conference Papers and Presentations Formulating Concepts for Phase 3 Research Plan

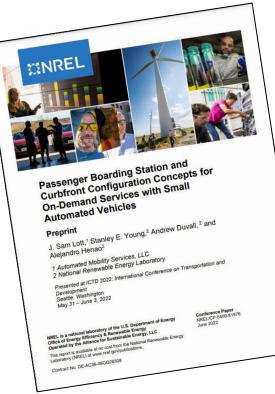
1. <u>Passenger Boarding Station and Curbfront</u> <u>Configuration Concepts for On-Demand</u> <u>Services with Small Automated Vehicles</u>

- Coauthors: J. Sam Lott; Stanley E. Young, Ph.D.; Andrew Duvall, Ph.D.; Alejandro Henao, Ph.D.
- Proceedings of the ASCE Intl. Conference on Transportation and Mobility, Automated People Mover and Automated Transit Systems, June 2022
- NREL Online Publication of Conference Paper:

https://www.nrel.gov/docs/fy22osti/81976.pdf

2. <u>Fleet Electrification for Small Vehicle On-</u> <u>Demand Services</u>

- ITS Texas Annual Meeting, San Marcos, TX; September
- Presenter: J. Sam Lott



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